

GPS Radiosonde

iMS-100



Features:

Compact & Light Weight Radiosonde

- Much higher accurate measurements of temperature and humidity, wind for the upper-air soundings
- Light weight 38 g iMS-100 helps enhancing safe operation especially when it falls down to the ground.
- Tiny iMS-100 effectively reducing overall operational costs (smaller balloon, fewer gas consumption) depends on the target height
- Downsized iMS-100 can contribute to reduce environmental burden through the entire life cycle (manufacturing, transportation, storage, and disposal)
- One lithium battery enables more than 4 hours sounding operation.
- High stability transmitter complying with ETSI (EN 302 054 V1.1.1)
- Easy preparation through wireless infrared communication (IrDA) between radiosonde and sonde checker unit before launch
- •Biomaterial package, which is environmental friendly, is optionally available

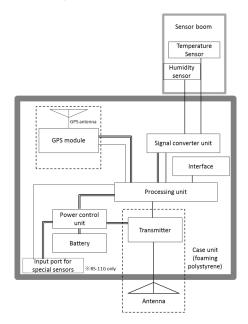
Outline

GPS radiosonde is an upper-air sounding instrument to measure various types of meteorological data; wind speed, wind direction, pressure, temperature and humidity. Wind speed, wind direction and pressure are calculated from the travel speed and altitude obtained by GPS positioning techniques. Every 1 second measured data are transmitted to ground receiving system via 400-406 MHz band.

Compact and commonly-used devices are aggressively adopted in iMS-100 to achieve downsizing (just only 38 g including one battery) and its cost reduction. iMS-100 also serves for total operation cost saving by using smaller balloon and reducing the gas amount depending on the target height. Furthermore, the lightweight package greatly enhances safety in the sounding operation even without parachute when it accidently falls down on land, especially.

Improved sensor boom achieves higher accuracy in temperature measurement. Also, newly developed high response humidity sensor enables more accurate humidity measurement even in low temperature environment (below –40°C). In addition to the advantages of cost and safety, the innovative downsizing can minimize pendulum motions and heat contamination from the sonde itself during launch, which improves the measurement performances in terms of wind and temperature.

Block Diagrams







404.5 MHz

< 15 kHz

FΜ

< 100 mW

Digital PCM

1,200 bps

1 second

3.0 VDC

< 200 mA

> 240 min.

EN302 054 V1.1.1

>300 km (with Yagi antenna)

Lithium battery × 1 (CR-123)

55(W)×53(D)×131(H) mm

40 g (Bio-based package)*8

Optional, please contact us.

10m/15m/30 m

400 MHz ~ 406MHz

Specifications (Uncertainty evaluation*1)

	Measurement range	-95°C to +60°C			
Temperature	Resolution Uncertainty*2	0.1°C Daytime: 0 to 16km : <0.5°C Above 16km : <0.8°C Night time:	Transmitter		
		0 to 16km : <0.4°C Above 16km : <0.4°C			
	Response time	< 0.4 s (1,000 hPa, 5 m/s)			
	Measurement range		Modulation		
	Resolution	0.1%RH			
Humidity	Uncertainty*2	0 to 12km: <5%RH*3 12 to 17km: <5%RH			
	Response time	< 0.2 s (Absorbing, 1,000 hPa, 6 m/s , 0°C) $<$ 14 s (Absorbing, 1,000 hPa, 6 m/s, -60°C)	Power		
	Measurement range	1050.0 hPa to 3.0 hPa			
	Resolution	0.1 hPa			
Pressure		1km:<1.2hPa	Size & Weight *		
	Uncertainty* ^{2,4}	10km:<1.2hPa 16km:<0.5hPa			
		24km : <0.5hPa	Accompanying		
		32km : <0.13hPa	items		
	Measurement range	-500 m to 40,000 m	NT 4		
	Resolution	0.1 gpm	Note		
Geopotential		1km:<11gpm 5km:<11gpm	*1) The uncertainty evaluation		
Height	Uncertainty*2,4	10km:<11gpm	*2) Expressed with co		
	Uncertainty ³	16km:<11gpm	*3) Expect rapid hum *4) Under optimal co		
		20km:<11gpm 32km:<11gpm	*5) 1σ statistical un scenario		
	Measurement range	32km:<11gpm	scenario *6) Frequency can be		
	Measurement range	32km:<11gpm 0° to 360°	*6) Frequency can be 406 MHz. Applie *7) Dimensions exclu		
Wind	Measurement range Resolution	32km:<11gpm 0° to 360° 0.01°	scenario *6) Frequency can be 406 MHz. Applie		
Wind Direction		32km:<11gpm 0° to 360°	*6) Frequency can be 406 MHz. Applie *7) Dimensions exclu		
Direction	Resolution	32km:<11gpm 0° to 360° 0.01° 0 to 16km:<1°with speed<10m/s <1° with speed >10m/s Above 16km:<1°with speed<10m/s <1° with speed>10m/s	*6) Frequency can be 406 MHz. Applie *7) Dimensions exclu *8) Bio-based materi		
Direction	Resolution Uncertainty*45	32km:<11gpm 0° to 360° 0.01° 0 to 16km:<1°with speed<10m/s <1° with speed >10m/s Above 16km:<1°with speed<10m/s <1° with speed>10m/s	*6) Frequency can be 406 MHz. Applie *7) Dimensions exclu *8) Bio-based materi		
Direction	Resolution Uncertainty*45 Measurement range	32km: <11gpm 0° to 360° 0.01° 0 to 16km:<1°with speed<10m/s <1° with speed >10m/s Above 16km:<1°with speed<10m/s <1° with speed >10m/s 0 m/s to 200 m/s	*6) Frequency can be 406 MHz. Applie *7) Dimensions exclu *8) Bio-based materi		
Direction	Resolution Uncertainty*45 Measurement range Resolution	32km: <11gpm 0° to 360° 0.01° 0to 16km:<1°with speed<10m/s <1° with speed >10m/s Above 16km:<1°with speed<10m/s <1° with speed >10m/s 0 m/s to 200 m/s 0.01 m/s 0 to 16km: <0.15m/s	*6) Frequency can be 406 MHz. Applie *7) Dimensions exclu *8) Bio-based materi		
Direction Wind	Resolution Uncertainty*4,5 Measurement range Resolution Uncertainty*4,5	32km:<11gpm 0° to 360° 0.01° 0 to 16km:<1°with speed<10m/s <1° with speed>10m/s Above 16km:<1°with speed>10m/s <1° with speed>10m/s 0 m/s to 200 m/s 0.01 m/s 0 to 16km:<0.15m/s Above 16km:<0.15m/s	*6) Frequency can be 406 MHz. Applie *7) Dimensions exclu *8) Bio-based materi		
Direction Wind Speed	Resolution Uncertainty*4,5 Measurement range Resolution Uncertainty*4,5 Frequency	32km:<11gpm 0° to 360° 0.01° 0 to 16km:<1°with speed<10m/s <1°with speed >10m/s Above 16km:<1°with speed<10m/s <1°with speed >10m/s 0 m/s to 200 m/s 0.01 m/s 0 to 16km:<0.15m/s Above 16km:<0.15m/s Above 16km:<1.25m/s Above 16km:<0.45m/s	*6) Frequency can be 406 MHz. Applie *7) Dimensions exclu *8) Bio-based materi		
Direction Wind Speed GPS Receiver	Resolution Uncertainty*45 Measurement range Resolution Uncertainty*45 Frequency Number of channels	32km:<11gpm 0° to 360° 0.01° 0 to 16km:<1°with speed<10m/s <1°with speed >10m/s Above 16km:<1°with speed<10m/s <1°with speed >10m/s 0 m/s to 200 m/s 0.01 m/s 0 to 16km:<0.15m/s Above 16km:<0.15m/s Above 16km:<1.25m/s Above 16km:<0.45m/s	*6) Frequency can be 406 MHz. Applic *7) Dimensions exclu *8) Bio-based materi		
Direction Wind Speed	Resolution Uncertainty*45 Measurement range Resolution Uncertainty*45 Frequency Number of channels Positioning Technology	32km:<11gpm 0° to 360° 0.01° 0 to 16km:<1°with speed<10m/s <1°with speed>10m/s Above 16km:<1°with speed<10m/s <1°with speed>10m/s 0 m/s to 200 m/s 0.01 m/s 0 to 16km:<0.15m/s Above 16km:<0.15m/s Above 16km:<0.15m/s Apove 16km:<0.15m/s Apove 16km:<0.15m/s Above 16km:<0.15m/s	*6) Frequency can be 406 MHz. Applie *7) Dimensions exclu *8) Bio-based materi		

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- The uncertainty values are calculated by the latest (April, 2016) JMA-GRUAN evaluation
 Expressed with coverage factor, k=2, unless otherwise explicitly specified.

Center freq.

Band width

Standard Modulation type

Baud rate

Sampling

Voltage

Current

Battery type

Dimensions

Weight (Including a battery)

Unwinder

Balloon/parachute

Operating time

Range

Output power

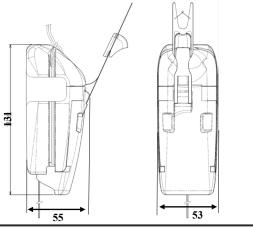
Transmitter type

Tuning range *6

- Expect rapid humidity change around tropopause
 Under optimal conditions of GPS reception: PDOP = 1 1σ statistical uncertainty evaluated with GPS simulator by using sonde sounding scenario
- Frequency can be changed every 100 kHz within the tuning range of 400 MHz and 406 MHz. Applicable Radio Law/Regulations should be complied.
- Dimensions excluding antenna and sensor boom. Weight includes a battery, etc. Bio-based material package type is optionally available.

utline View

Unit (mm)





Cautions

Humidity

- For safe and correct usage, please read the "Operation Manual" prior to the use of the products.
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0%RH to 100%RH

- The specifications shown in the catalog are of our standard products. We are pleased to customize it to meet customer's requirements. For the details, please contact us.
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GROUND RECEIVER SYSTEM RD-18 w/ Sounding Software MGPS2



GPS Radiosonde Ground Receiver System efficiently responds to the operator's requirements for upper air sounding operation. The lightweight and simple system is allows easier installation.

<u>Inside equipment</u> consists of PC with sounding software MGPS2, sonde checker, PoE injector, GPS re-radiator.

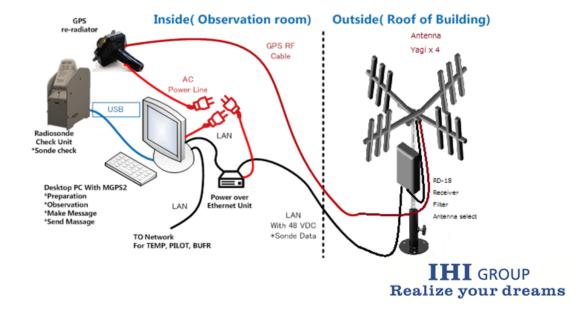
MGPS2 is easy to use sounding software even for non-trained operator supporting preparation, sonde check, launch, data collection, analysis and various meteorological messages through interactive interface. In addition to fundamental charts, various applications are provided such as Emagram, Skew-T, Hodograph and so on. MGPS2 can also display the status of RD-18 receiver (the receiver frequency, signal strength and real time spectrum etc.). MGP2 can operate in any time zone (LST or UTC) and receives time information from the sonde synchronized with the GPS time and synchronizes the its time.

Features

- Easy installation (1 pole for outside equipment. 1
 Ethernet cable between inside and outside)
 *Except for a coaxial cable for GPS rerepeater
- ▼ Three (3) steps to facilitate sounding operation
- Quick five (5) minutes preparation
 * The time to display the corrected data depends on the setting of the filter

<u>Outside equipment</u> consists of 400MHz antennas (maximum 4) for radiosonde, RD-18 receiver and GPS antenna.

RD-18 receiver is installed beneath the antenna. RD-18 receives signal of the radiosonde, demodulates the signal, sends measured data to indoor PC by a Ethernet cable. RD-18 consumes less power and it is powered from PoE injector by the Ethernet cable. By selecting the PoE injector compatible with each country's power supply, it can be used in any power supply environment. RD-18 has backup capacitor inside, so it keeps working against momentary power failure. RD-18 also sends HK data (lock status, inside temperature and the status of power supply) to PC. RD-18 has other basic functions, such as antenna switcher, narrow 8ch band pass filter, AFC/MFC and real time spectrum measurement. RD-18 can receive the signal from radiosonde more than 250km away with Yagi antenna. Under low-temperature environment less than -20°C, it is possible to correspond up to -60°C by an optional external power supply and a heater.



Technical Data



RD-18 Receiver

KD-10 Kete	1761				
Receiver	Frequency Range	400.2 to 406 MHz	Environmental condition	Temperature	-20∼50°C
	Channel step	100 kHz (60ch)			-60∼50°C with optional heater
	Sensitivity	<-107[dBm]		Humidity	0~100%RH
	Function	AFC, AGC		Wind speed	Up to 60m/s(Instantaneous)
	Modulation type	РСМ-ҒМ ВіФ		Precipitation	Unlimited
	Deviation	⟨3.75kHz		Lightning	RF : SMA type
	Speed	1200bps			DC discharge starting >DC120V
	Band width	<15kHz			Voltage protection level <700V
	Error correction	BCH, 1bit error correction			Impulse durability 10kA(8/20us)
Port	Antenna	4ch, N-Jack			LAN: RJ-45 type
	Data & Power	RJ-45			DC discharge starting >DC60V
	Heater	2 pin connector			Voltage protection level <500V
Preamp	Gain	>20dB			Impulse durability 5kA(8/20us)
	Filter	8ch BPF		Water/Dust proof	IP65
		Band width: about 1MHz	Conn	Material	Aluminum diecast
Communication	to PC	LAN(10/100BASE-T)	Case	Size	W240 x H 360 x D 120
	Voltage	48V DC		Weight	<7kg
	Consumption	by PoE injector	Other functions	Antenna switch	Max 4ch
		<30W		Spectrum search	Real time
Power	Option: 100W heater		Yagi antenna		
		in cold area	Gain		>6.8[dBi]
	Extra	24V DC for optional heater	Directionality	Vertical	±35°
	Backup	1sec by backup capacitor		Horizontal	±45°
Indicator	Blue	Signal LOCK	Frequency	center	403MHz
	Green	Power On	Impedance	Input	50ohm
	Red	HK Warning	Range		>250km

Sounding software "MGPS2"

Display	PTU chart, Tracking chart, Ascent chart, Raw data, List table, Adiabatic diagrams (Emagram, Skew-T, Tephigram, Stuve diagram), Hodograph, Tu significant point editor, WMO Messages monitor, GPS status monitor, Radio frequency setting
Meteorological Data (Range & resolution)	Temperature: -95 +60°C, 0.1°C Humidity: 0 100%RH, 0.1°C Pressure: 1050.0hPa 3.0hPa, 0.1hPa Geopotential height: -500.0m 40000.0m, 0.1hPa Wind direction: 0.00° 359.99°, 0.01° Wind speed: 0.00m/s 200.00m/s, 0.01m/s
Meteorological Messages (WMO)	FM35 TEMP,FM36 TEMP SHIP, FM32 PILOT, FM75 CLIMAT TEMP BUFR 3'09'052 (for TEMP data) BUFR 3'09'050 and BUFR 3'09'051 (for PILOT data)
Meteorological messages (Military)	METCM, METB, METFM, METSR, METTA, METEO 11
Language	English, Spanish, Turkish and Japanese

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